

# Homework Sheet 11

**E1** Assume that for some function  $\alpha \in C^2(\mathbb{R}^+)$  and a delay fct.  $\beta \in C^2(\mathbb{R}^+)$ ,  $\beta \geq 0$ , there ex. for all profiles  $\phi \in C^2(\mathbb{R})$  solutions of the wave equation in  $\mathbb{R} \times (\mathbb{R}^d \setminus \{0\})$  having the form

$$u(t, x) = \alpha(r) \phi(t - \beta(r))$$

Here  $r = |x|$  and we assume  $\beta(0) = 0$ . Show that this possible only if  $d=1$  or  $d=3$ , and compute the form of the fct.  $\alpha, \beta$ .

Proof.  $\frac{d^2}{dt^2} u(t, x) = \alpha(r) \phi''(t - \beta(r))$

$$\begin{aligned} \Delta u(t, x) &= \underbrace{\Delta(\alpha(r))}_{=\alpha''(r) + (d-1)\alpha'(r)\frac{1}{r}} \phi(t - \beta(r)) + 2 \underbrace{\nabla(\alpha(r))}_{=\frac{\alpha'(r)}{r}} \cdot \underbrace{\nabla(\phi(t - \beta(r)))}_{=-\phi'(t - \beta(r))\beta'(r)\frac{x}{r}} + \alpha(r) \underbrace{\Delta(\phi(t - \beta(r)))}_{=\phi''(t - \beta(r))(\beta'(r))^2 - \phi'(t - \beta(r))\beta''(r) - (d-1)\phi'(t - \beta(r))\beta'(r)\frac{1}{r}} \end{aligned}$$

$$\begin{aligned} \Rightarrow -\frac{d^2}{dt^2} u(t, x) + \Delta u(t, x) &= \phi(t - \beta(r)) \left( \alpha''(r) + (d-1)\alpha'(r)\frac{1}{r} \right) \\ &\quad + \phi'(t - \beta(r)) \left( 2\alpha'(r)\beta'(r) - \alpha(r)\beta''(r) - \alpha(r)(d-1)\beta'(r)\frac{1}{r} \right) \\ &\quad + \phi''(t - \beta(r)) \left( \alpha(r)(\beta'(r))^2 - \alpha(r) \right) \stackrel{!}{=} 0 \end{aligned}$$

Choose  $\phi \equiv \text{const.} \Rightarrow 0 = \alpha''(r) + (d-1)\alpha'(r)\frac{1}{r}$  (I)

Choose  $\phi' \equiv \text{const.} \Rightarrow 0 = 2\alpha'(r)\beta'(r) + \alpha(r)\beta''(r) + (d-1)\alpha(r)\beta'(r)\frac{1}{r}$  (II)

Choose  $\phi'' \equiv \text{const.} \Rightarrow 0 = \alpha(r)(\beta'(r))^2 - \alpha(r)$  (III)

(III)  $\Rightarrow \beta'(r) = 1$  if  $\alpha(r) \neq 0$ ,

(II)  $\Rightarrow 0 = 2\alpha'(r) + (d-1)\alpha(r)\frac{1}{r}$

Let  $a < b$  such that  $\alpha|_{[a, b]} \neq 0 \Rightarrow \forall r \in [a, b] : \frac{d}{dr} \ln \alpha(r) = \frac{\alpha'(r)}{\alpha(r)} = \frac{1-d}{2} \frac{1}{r}$

$$\Rightarrow \ln \alpha(r) - \ln \alpha(a) = \int_a^r \frac{d}{ds} \ln \alpha(s) ds = \int_a^r \frac{1-d}{2s} ds = \frac{1-d}{2} \ln r - \frac{1-d}{2} \ln a$$

$$\Rightarrow \alpha(r) = \text{const.} \cdot r^{\frac{1-d}{2}}$$

1. case  $d=1$ :  $\Rightarrow \alpha|_{[a, b]} = \text{const.}$ , by iteration one gets  $\alpha|_{\mathbb{R}^+} = \text{const.}$ , with  $\beta'(r) = 1 \Rightarrow \beta(r) = r$  and all three equations are fulfilled.



2. case.  $d \neq 1$ :  $\Rightarrow$  (I)  $0 = \text{const.} \cdot \left( \frac{1-d}{2} \left( \frac{1-d}{2} - 1 \right) + (d-1) \frac{1-d}{2} \right) r^{\frac{1-d}{2} - 1}$  for  $r \in [a, b]$

$$\Rightarrow 0 = \frac{1-d}{2} \left( \frac{1-d}{2} - 1 \right) + (d-1) \frac{1-d}{2} = -\frac{1}{4} (d-1)(d-3)$$

$\Rightarrow$  only possible if  $d=3$ .

Choose  $\alpha(r) = \text{const.} \cdot r^{\frac{1-d}{2}}$ ,  $\beta(r) = r \Rightarrow$  all three equations are fulfilled. □

E2

Let  $g = \text{diag}(-1, 1, 1, 1) \in \mathbb{R}^{4 \times 4}$ . A real  $4 \times 4$  matrix  $\Lambda \in \mathbb{R}^{4 \times 4}$  is called a Lorentz transformation if and only if  $\Lambda^T g \Lambda = g$ , where  $\Lambda^T$  denotes the transpose of  $\Lambda$ .

(i) The product of two Lorentz transformations is also a Lorentz transformation.

Proof.  $\Lambda_1, \Lambda_2 \in \mathbb{R}^{4 \times 4}$ ,  $\Lambda_i^T g \Lambda_i = g$  for  $i \in \{1, 2\} \Rightarrow (\Lambda_1 \Lambda_2)^T g \Lambda_1 \Lambda_2 = \Lambda_2^T \underbrace{\Lambda_1^T g \Lambda_1}_{=g} \Lambda_2 = \Lambda_2^T g \Lambda_2 = g$

(ii) Every Lorentz. transf. is invertible and its inverse is a Lorentz transf., too.

Proof.  $\Lambda$  Lorentz transf.  $\Rightarrow g = \Lambda^T g \Lambda \Rightarrow \dim \ker \Lambda \leq \dim \ker \Lambda^T g \Lambda = \dim \ker g = 0$   
 $\Rightarrow \ker \Lambda = \{0\} \Rightarrow \Lambda$  invertible  $\Rightarrow (\Lambda^{-1})^T g \Lambda^{-1} = (\Lambda^{-1})^T \Lambda^T g \Lambda \Lambda^{-1} = \underbrace{(\Lambda \Lambda^{-1})^T}_{=I} g (\Lambda \Lambda^{-1}) = g$   
 $\Rightarrow \Lambda^{-1}$  is Lorentz transformation.

(iii) Define the quadratic form  $\langle x, y \rangle_g := x^T g y$  for  $x, y \in \mathbb{R}^4$ .  $\Rightarrow \forall \Lambda$  Lorentz transf.  $\langle \Lambda x, \Lambda y \rangle_g = \langle x, y \rangle_g$

Proof.  $\forall x, y \in \mathbb{R}^4$ :  $\langle \Lambda x, \Lambda y \rangle_g = (\Lambda x)^T g \Lambda y = x^T \Lambda^T g \Lambda y = x^T g y = \langle x, y \rangle_g$

(iv) The following are Lorentz transformations (where  $(t, x) \in \mathbb{R}^4$ ,  $t \in \mathbb{R}$ ,  $x \in \mathbb{R}^3$ )

(a)  $(t, x) \mapsto (t, Qx)$  where  $Q$  is an orthogonal transformation of  $\mathbb{R}^3$

(b)  $(t, x) \mapsto (-t, x)$

(c)  $(t, x) \mapsto \left( \frac{t - ax_1}{\sqrt{1-a^2}}, \frac{x_1 - at}{\sqrt{1-a^2}}, x_2, x_3 \right)$ , where  $0 < a < 1$

Proof. (a)  $\Lambda_1 = \begin{pmatrix} 1 & 0 \\ 0 & Q \end{pmatrix} \Rightarrow \Lambda_1^T g \Lambda_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & Q^T & & \\ 0 & & 1 & 0 \\ 0 & & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & Q & & \\ 0 & & 1 & 0 \\ 0 & & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & Q^T Q & & \\ 0 & & 1 & 0 \\ 0 & & 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = g$

(b)  $\Lambda_2 = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = g \Rightarrow \Lambda_2^T g \Lambda_2 = g^3 = \underbrace{g^2}_{=I_4} \cdot g = g$

(c)  $\Lambda_3 = \begin{pmatrix} 1 & -a & 0 & 0 \\ \frac{-a}{\sqrt{1-a^2}} & \frac{1}{\sqrt{1-a^2}} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \Lambda_3^T g \Lambda_3 = \begin{pmatrix} 1 & \frac{-a}{\sqrt{1-a^2}} & 0 & 0 \\ \frac{-a}{\sqrt{1-a^2}} & \frac{1}{\sqrt{1-a^2}} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} 1 & -a & & \\ \frac{-a}{\sqrt{1-a^2}} & \frac{1}{\sqrt{1-a^2}} & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$   
 $= \frac{1}{1-a^2} \begin{pmatrix} (1-a) \cdot (-1) \cdot (1-a) & 0 & & \\ -a & 1 & & \\ 0 & & (1-a^2) \cdot (1) \cdot (1) & \\ 0 & & & (1) \cdot (1) \cdot (1) \end{pmatrix} = \begin{pmatrix} \frac{1}{1-a^2} (1-a) \cdot (-1) \cdot (1-a) & 0 & & \\ 0 & 1 & & \\ 0 & & 1 & \\ 0 & & & 1 \end{pmatrix} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$

(v) The wave equation is Lorentz-covariant, i.e. if  $u_{tt} - \Delta u = 0$  in  $\mathbb{R}^4 \Rightarrow v(\cdot) := u(\Lambda \cdot)$  is also a solution to the wave eq.

Proof.  $\frac{\partial^2}{\partial t^2} - \Delta = \begin{pmatrix} \frac{\partial}{\partial t} \\ \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \frac{\partial}{\partial x_3} \end{pmatrix}^T g \begin{pmatrix} \frac{\partial}{\partial t} \\ \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \frac{\partial}{\partial x_3} \end{pmatrix} = \nabla^T g \nabla \Rightarrow \left( \frac{\partial^2}{\partial t^2} - \Delta \right) v(x) = \nabla^T g \nabla (u(\Lambda x)) = \nabla^T \left( g \cdot \Lambda^T \nabla u(\Lambda x) \right) = \nabla^T \Lambda^T g \Lambda \nabla u(\Lambda x) = \underbrace{(\nabla^T g \nabla)}_{=0} u(\Lambda x) = 0$

□

**E3** Let  $S := \{(t, x) : x \in \mathbb{R}^3\} \subset \mathbb{R}^4$  be a smooth hypersurface (i.e.  $\phi \in C^\infty(\mathbb{R}^3)$ ) The Cauchy problem for the wave equation with initial surface  $S_a$  is: 
$$\begin{cases} u_{tt} - \Delta u = 0 & \text{in } \mathbb{R}^4 \\ u = g & \text{on } S_a \end{cases} \quad (1)$$

We say, that  $S$  is space like if  $1 - |\nabla \phi|^2 > 0$  on  $\mathbb{R}^3$ .

$\Rightarrow$  The Cauchy problem for the wave equation with the space-like initial surface  $S_a = \{(t, x) \in \mathbb{R}^4 : t = ax_1\}$ ,  $0 < a < 1$ , is equivalent to the initial value problem (i.e. when  $S_0 = \{(t, x) \in \mathbb{R}^4 : t = 0\}$ )

Proof. Note  $S_a$  is indeed space-like, since for  $\phi(x) := ax_1$ ,  $1 - |\nabla \phi|^2 = 1 - a^2 > 0$

Note further, that  $\Lambda_3(a)S_a \subseteq S_0$  and  $\Lambda_3(-a)S_0 \subseteq S_a$ ,

since  $\forall (t, x) \in S_a : \Lambda_3(a)\begin{pmatrix} t \\ x \end{pmatrix} = \begin{pmatrix} \frac{t-ax_1}{1-a^2}, \frac{x_1-at}{1-a^2}, x_2, x_3 \end{pmatrix} = \begin{pmatrix} 0, \frac{x_1-at}{1-a^2}, x_2, x_3 \end{pmatrix} \in S_0$

and  $\forall (t, x) \in S_0 : \Lambda_3(-a)\begin{pmatrix} t \\ x \end{pmatrix} = \begin{pmatrix} \frac{0+ax_1}{1-a^2}, \frac{x_1+a0}{1-a^2}, x_2, x_3 \end{pmatrix} = \begin{pmatrix} a\frac{x_1}{1-a^2}, \frac{x_1}{1-a^2}, x_2, x_3 \end{pmatrix} \in S_a$

$\Rightarrow S_0 \subseteq \Lambda_3(-a)S_a = \Lambda_3(a)S_a \subseteq S_0 \Rightarrow S_0 = \Lambda_3(a)S_a$

Let be  $u$  a solution of (1)  $\Rightarrow v(t, x) := v(\Lambda_3(-a)(t, x)^T)$  is also a solution to the wave equation  $E_2(v)$  to the initial values  $v(0, x) = g(\underbrace{\Lambda_3(-a)(0, x)}_{\in S_a})$ . □

**E4** Let  $n=3$  or  $n=2$ , and let  $u \in C^2(\mathbb{R}^n \times [0, \infty))$  be the solution of 
$$\begin{cases} u_{tt} - \Delta u = 0 & \text{in } \mathbb{R}^n \times (0, \infty) \\ u = 0, u_t = h & \text{in } \mathbb{R}^n \times \{t=0\} \end{cases}$$
 with  $h \in C_c^2(\mathbb{R}^n)$ , given by Kirchhoff's formula or Poisson's formula, respectively.

(i) Let  $\alpha \in (0, 1)$ . There ex. Constants  $C_3, C_2 > 0$ , depending on the support of  $h$  (and on  $\alpha$  in the second case) such that for all  $t > 0$

$$\sup_{x \in \mathbb{R}^3} |u(t, x)| \leq \frac{C_3}{t} \sup_{\mathbb{R}^3} |h| \quad (n=3), \quad \sup_{x \in B_{\alpha t}(0)} |u(t, x)| \leq \frac{C_2}{t} \sup_{\mathbb{R}^2} |h| \quad (n=2)$$

Proof.  $n=3$ :  $u(t, x) = \int_{\partial B_t(x)} t h(y) dS(y)$  (Kirchhoff)

$$n=2: u(t, x) = \frac{1}{2} \int_{B_t(x)} \frac{t^2 h(y)}{(t^2 - |y-x|^2)^{1/2}} dy$$

$n=2$ :  $\forall x \in B_{\alpha t}(0), \forall y \in \text{supp } h \subseteq B_R(0) : |y-x| \leq R + \alpha t$ .

Choose  $\varepsilon \in (0, 1)$  such that  $\alpha \leq (1 - \varepsilon^2)^{1/2} \Rightarrow \exists t_0 > 0 \forall t \geq t_0 |y-x| \leq R + \alpha t \leq (1 - \varepsilon^2)^{1/2} t$

$$\Rightarrow (t^2 - |y-x|^2)^{1/2} \geq (t^2 - (1 - \varepsilon^2)t^2)^{1/2} = \varepsilon t$$

$$\Rightarrow |u(t, x)| \leq \frac{1}{2} \frac{1}{\pi t^2} \int_{B_t(x)} \frac{t^2 |h(y)|}{(t^2 - |y-x|^2)^{1/2}} dy \leq \frac{1}{2\pi} \int_{B_t(x)} \frac{|h(y)|}{\varepsilon t} dy \leq \frac{1}{2\pi} \frac{|\text{supp } h|}{\pi R^2} \frac{1}{\varepsilon t} \|h\|_\infty \quad \text{f.a. } x \in B_{\alpha t}(0) \quad t \geq t_0$$

$$\text{and } |u(t, x)| \leq \frac{1}{2\pi} \int_{B_t(x)} \frac{|h(y)|}{(t^2 - |y-x|^2)^{1/2}} dy = \frac{1}{2\pi t} \int_{B_t(x)} \frac{|h(y)|}{(1 - |y-x|^2/t^2)^{1/2}} dy$$

$$= \frac{1}{2\pi t} \int_{B_1(0)} \frac{\|h\|_\infty}{(1 - |y|^2)^{1/2}} t^2 dy = \frac{1}{2\pi} \int_0^1 \frac{r}{(1-r^2)^{1/2}} dr \|h\|_\infty \leq \frac{t_0}{t} \|h\|_\infty \quad \text{f.a. } x \in B_{\alpha t}(0) \quad t \geq t_0$$

$$= \frac{1}{2\pi} \int_0^1 \frac{r}{(-\sqrt{1-r^2})} dr \|h\|_\infty$$

$n=3$ : Let  $R > 0$  be a constant with  $\text{supp } h \subseteq B_R(0) \Rightarrow \forall x \in \mathbb{R}^3$ , and  $\forall r > 0 \lambda_2(\partial B_r(x) \cap \text{supp } h) = \lambda_2(\partial B_r(0)) = 4\pi r^2$

$$\Rightarrow |u(t, x)| \leq \left| \int_{\partial B_t(x)} t h(y) dS(y) \right| \leq \frac{t}{4\pi t^2} \int_{\substack{\partial B_t(x) \\ \cap \text{supp } h}} \|h\|_\infty dS(y) \leq \frac{1}{t} R^2 \|h\|_\infty$$

(ii)  $n=3$ :  $\sup |u(t,x)| \leq \frac{1}{4\pi} \min\left(\frac{1}{t} \|Dh\|_{L^1(\mathbb{R}^3)}, \|D^2h\|_{L^1(\mathbb{R}^3)}\right)$ , for  $t > 0$

Proof.  $|u(t,x)| \leq \left| \int_{\partial B_t(x)} \frac{1}{4\pi t^2} h(y) dS(y) \right| = \left| \frac{1}{4\pi t^2} \int_{\partial B_t(x)} h(y) dS(y) \right| = \left| \frac{1}{4\pi} \int_{\partial B_1(0)} h(x+tz) dS(z) \right|$

$$= \left| \frac{1}{4\pi} \int_{\partial B_1(0)} \int_t^\infty h(x+sz) ds dz \right| = \frac{t}{4\pi} \left| \int_{\partial B_1(0)} \int_t^\infty Dh(x+sz) \cdot z ds dz \right|$$

$$\leq \int_t^\infty \int_{\partial B_1(0)} |Dh(x+sz)| dz ds \leq \frac{1}{t} \int_0^\infty \int_{\partial B_1(0)} |Dh(x+sz)| dz s^2 ds = \frac{1}{4\pi t} \|Dh\|_{L^1}$$

Coarea-Formula

$\leq \frac{s^2}{t}$ , since  $t \leq s$

and  $|u(t,x)| \leq \frac{1}{4\pi} t \left| \int_{\partial B_t(0)} \int_t^\infty \int_s^\infty h(x+uz) du ds dz \right| = \frac{t}{4\pi} \left| \int_{\partial B_t(0)} \int_t^\infty \int_s^\infty \frac{\partial^2 h}{\partial u^2}(x+uz) du ds dz \right|$

$$= \langle z, D^2h(x+uz)z \rangle$$

Tanelli  $\int \leq \frac{t}{4\pi} \left| \int_{\partial B_t(0)} \int_t^\infty \int_t^u |\frac{\partial^2 h}{\partial u^2}(x+uz)| ds du dz \right| = \frac{1}{4\pi} \int_{\partial B_t(0)} \int_t^\infty \frac{t(u-t)}{t} |\frac{\partial^2 h}{\partial u^2}(x+uz)| du dz = \frac{1}{4\pi} \|D^2h\|_{L^1}$

Coarea Formula

$\leq u^2 \leq \|D^2h(x+uz)\|$