

40. Gauge Field Theories

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So far, we have described the kinematics of gauge field theories - if at all.

We come to the dynamics, - mainly in the special case of Yang Mills theory.

Fixed data are:

M a semi-Riemannian oriented manifold of dim. n .

G a Lie group with its Lie algebra \mathfrak{g} .

β a symmetric, \mathbb{R} -bilinear form $\mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{R}$, $\det \beta \neq 0$,
and bi-invariant ($\beta(\alpha_g X, \alpha_g Y) = \beta(X, Y)$, $X, Y \in \mathfrak{g}$).

Moreover, we study principal fiber bundles

$\xi = (P, \pi, M, G)$ with M and G given.

(40.1) DEFINITION: The configuration space of pure YM theory is the space

$$\begin{aligned} \mathcal{A} = \mathcal{A}(P) &= \{ \omega \in \mathcal{A}^1(P, \mathfrak{g}) : \omega \text{ connection form} \} \\ &\cong \omega_0 + \mathcal{A}^1(M, \text{Ad} P) \quad (\text{cf. 38.6}) \end{aligned}$$

The YM-density is $\mathcal{L}(\omega) := -\frac{1}{2} \|\Omega^\omega\|^2$, $\omega \in \mathcal{A}$.

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Here, $\|\Omega\|^2|_U = (\Omega, \Omega)|_U = \beta(F_{\mu\nu}, g^{\mu\lambda} g^{\nu\kappa} F_{\lambda\kappa})$ where $F = s^*\Omega$ for a section $s: U \rightarrow P$ and $F = F_{\mu\nu} dq^\mu \wedge dq^\nu$ in local coordinates. The expression is independent of the choice of the section since β is bi-invariant. Therefore, it extends to all of M .

(40.2) DEFINITION: The motions of the system are the stationary points of the action functional

$$S(\omega) := \int_M \mathcal{L}(\omega) \text{vol}_M,$$

i.e.

$$\omega \text{ motion} \Leftrightarrow \forall \eta \in \mathcal{A}^1(M, \text{Ad}P): \left. \frac{d}{d\varepsilon} S(\omega + \varepsilon\eta) \right|_{\varepsilon=0} = 0$$

(40.3) PROPOSITION: The equations of motion are

$$D^*\Omega = 0.$$

Here $D = D^\omega$ is the covariant differential, $\Omega = \Omega^\omega$ is the curvature and D^* is the adjoint of D

Pf.
$$\begin{aligned} \Omega^{\omega + \varepsilon\eta} &= D^{\omega + \varepsilon\eta}(\omega + \varepsilon\eta) = d(\omega + \varepsilon\eta) + \frac{1}{2} [(\omega + \varepsilon\eta), (\omega + \varepsilon\eta)] \\ &= \left(d\omega + \frac{1}{2} [\omega, \omega] \right) + \varepsilon \left(d\eta + \frac{1}{2} ([\omega, \eta] + [\eta, \omega]) \right) + \frac{1}{2} \varepsilon^2 [\eta, \eta] \end{aligned}$$

By 39.8 we have $D\eta = d\eta + [\omega, \eta]$ for $\eta \in \mathcal{A}^1(M, \text{Ad } P)$, hence.

$$\Omega^{\omega + \varepsilon\eta} = \Omega^\omega + \varepsilon D^\omega \eta + \frac{1}{2} \varepsilon^2 [\eta, \eta].$$

It follows: ω motion

$$\Leftrightarrow \int_M \frac{d}{d\varepsilon} \|\Omega^{\omega + \varepsilon\eta}\| \Big|_{\varepsilon=0} \text{vol} = 0$$

$\forall \eta$

$$\Leftrightarrow \int_M (\Omega^\omega, D^\omega \eta) \text{vol} = 0$$

$\forall \eta$

$$\Leftrightarrow \int_M (D^* \Omega, \eta) \text{vol} = 0$$

$\forall \eta$

$$\Leftrightarrow D^* \Omega = 0$$

□

(40.4) COROLLARY: The motions satisfy

$$D^* \Omega = 0 \quad \text{and} \quad D\Omega = 0.$$

(The Bianchi $D\Omega = 0$ is always satisfied.)

The operator D^* can also be described by the Hodge star product $*$. $*$ is induced by the metric and gives a map

$$* : \mathcal{A}^k(M) \rightarrow \mathcal{A}^{n-k}(M)$$

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such that $D^{\omega*} = \pm * D^{\omega} *$.

In the case of d and d^* on M with a Riemannian metric the Laplacian is

$$\Delta = dd^* + d^*d : \mathcal{A}^k \rightarrow \mathcal{A}^k,$$

and the forms γ with $\Delta\gamma = 0$ are the harmonic forms. Regarding 40.4 there is a close analogy between the YM-theory and the theory of harmonic forms (Hodge theory). Insofar, YM-theory is considered as a kind of nonabelian Hodge theory.

We want to describe how connections and curvatures change under general automorphisms

$\bar{\Phi} : \xi \rightarrow \xi$
of the pfb ξ (global gauge transformation).

(40.5) DEFINITION: A gauge transformation (automorphism) of ξ is given by a smooth $\bar{\Phi} : P \rightarrow P$ with $\pi \circ \bar{\Phi} = \pi$ and $\bar{\Phi} \circ \mathcal{F}_g = \mathcal{F}_g \circ \bar{\Phi}$ for all $g \in G$.

Let $\mathcal{G}(P)$ denote the group of gauge transformations. $\mathcal{G}(P)$ is in a natural bijection to

$$\Sigma(P, G)^G := \{ f: P \rightarrow G \mid f(pg) = g^{-1}f(p)g \}.$$

The bijection $f \mapsto \Phi_f$ is given by

$$\Phi_f(p) := pf(p), \quad p \in P.$$

Two connections ω and ω' which are related by a gauge transformation Φ in the manner

$$\omega' = \Phi^* \omega$$

describe the same physics and should be identified if they are related by $\omega' = \Phi^* \omega$. As a result instead of $\mathcal{A}(P)$ the quotient

$$\mathcal{A}(P)/\mathcal{G}(P) = \mathcal{A}(P)/\sim \quad (\omega' \sim \omega : \Leftrightarrow \exists \Phi \in \mathcal{G}(P) : \omega' = \Phi^* \omega)$$

is the true configuration space. The space $\mathcal{A}(P)/\mathcal{G}(P)$ of gauge orbits is not easy to handle since $\mathcal{A}(P)$ and $\mathcal{G}(P)$ are infinite dimensional (manifolds).

Comparing ω and $\Phi^* \omega$ we have the following

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(40.6) PROPOSITION: Let Φ be a gauge transformation on \mathbb{F} and let ω be a connection. Then $\Phi^*\omega$ is a connection as well and we have

$$\begin{aligned} 1^\circ \quad \Phi^*\omega &= \text{Ad}_{f^{-1}}\omega + f^*\kappa & (\Phi = \Phi_f) \\ 2^\circ \quad \Phi \circ \rho_g \Phi^* &= \rho_g \omega \circ \Phi & \kappa([g e^{tX}]) = X \\ 3^\circ \quad D^{\Phi^*\omega} \circ \Phi^* &= \Phi^* \circ D\omega \\ 4^\circ \quad \Omega^{\Phi^*\omega} &= \Phi^* \Omega\omega = \text{Ad}_{f^{-1}}\Omega\omega \end{aligned}$$

Pf. We only show that $\Phi^*\omega$ is a connection form:

For $X \in \mathfrak{g}$ and $\rho \in P$

$$T_\rho \Phi(X^*(\rho)) = T_\rho \Phi([p e^{tX}]_\rho) = [\Phi(p e^{tX})]_{\Phi(\rho)} = [\Phi(\rho) e^{tX}]_{\Phi(\rho)} = X^*(\Phi(\rho))$$

Hence, $\Phi^*\omega$ satisfies (w1):

$$\Phi^*\omega(X^*(\rho)) = \omega_{\Phi(\rho)}(T_\rho \Phi(X^*(\rho))) = \omega_{\Phi(\rho)}(X^*(\Phi(\rho))) = X,$$

But (w2) is satisfied, too:

$$\psi_g^* \Phi^*\omega = \Phi^* \psi_g^* \omega = \Phi^*(\text{Ad}_g^{-1}\omega) = \text{Ad}_g(\Phi^*\omega).$$

The rest of the proof is standard. Notice, that some of the formulas resemble the formulas for local gauge transformations, in particular 1° and 4° . In fact, looking at the definition of Φ_f it could be denoted as ψ_f as well,

and we would have $\psi_f^* \omega = \text{Ad}_f^{-1} \omega + f^* \kappa$ (1°) and $\psi_f^* \Omega = \text{Ad}_f^{-1} \Omega$ (4°).

It is in general difficult to describe solutions of the YM equations $D^* \Omega = 0$. But in the case of a 4 dim. Riemannian manifold M we can look for special solutions. In that case the Hodge operator on 2 forms maps into 2 forms

$$* : \mathcal{A}^2(M) \rightarrow \mathcal{A}^2(M)$$

To describe $*$ on $\mathcal{A}^2(M)$ we use the fact that the Riemannian metric induces a Riemannian metric on T^*M and for an orthonormal basis

$$\sigma_1, \sigma_2, \sigma_3, \sigma_4 \text{ in } T_a^*M$$

$$*(\sigma_1 \wedge \sigma_2) = \sigma_3 \wedge \sigma_4, \quad *(\sigma_1 \wedge \sigma_3) = -\sigma_2 \wedge \sigma_4 \quad \text{etc.}$$

$$*(\sigma_{i_1} \wedge \sigma_{i_2}) = \text{sgn}(i_1, i_2, i_3, i_4) \sigma_{i_3} \wedge \sigma_{i_4}, \quad \{i_1, i_2, i_3, i_4\} = \{1, 2, 3, 4\}$$

(40.7) DEFINITION: A two-form $\eta \in \mathcal{A}^2(M)$ is self-dual (resp. antiself-dual) if $*\eta = \eta$ (resp. $*\eta = -\eta$).

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A connection is self-dual (anti-self-dual) if Ω^ω is selfdual (anti-self-dual), as section $\Omega^\omega \in \mathcal{A}^2(M, \text{Ad}P)$.

(40.8) Proposition: Every self-dual connection is a YM-connection and the same is true for the anti-self-dual connections.

Pf. We use the presentation $D^* = -*D*$ and can show for $*\Omega = \pm\Omega$:

$$D^*\Omega = -*D*\Omega = -D(\pm\Omega) = 0 \quad (\text{Bianchi}). \quad \square$$

Self-dual connections are also called instantons.

On \mathbb{R}^4 with the euclidean metric they have been studied in great detail.

General gauge field theories: Only $\xi = (P, \pi, M, G)$ is fixed and a representation $\rho: G \rightarrow GL(r, \mathbb{C})$.

• all space of metrics (fixed signature p, q) on M

• $\mathcal{F} = \Gamma(M, E_\rho)$

$\mathcal{Q}: \mathcal{D} \rightarrow \mathcal{A}^n(M), \quad \mathcal{D} \subset \mathcal{M} \times \mathcal{F} \times \mathcal{A} \times \dots$

more dyn. variables

$$S = \int_M \mathcal{L}$$

$$\delta S = 0 \iff \text{Equations of motion.}$$

Conditions on \mathcal{L} :

1. Gauge invariance in case of $\mathcal{D} = \mathcal{A}$

$$\mathcal{L}(\Phi^* \omega) = \mathcal{L}(\omega) \quad \forall \Phi \in \mathcal{G}(P) \quad \text{Example: } \mathcal{L}_{YM}$$

Result. $\omega \sim \omega'$: ω motion $\iff \omega'$ motion

2. Gauge invariance in case of $\mathcal{D} = \mathcal{A} \times \mathcal{F}$

$$\mathcal{L}(\Phi^* \omega, \Phi^* s) = \mathcal{L}(\omega, s) \quad \forall \Phi \in \mathcal{G}(P)$$

$$(s(a) = [p, f_s(p)] \Rightarrow \Phi^* s(a) = [p, f_s \circ \Phi(p)])$$

"Same" result!

3. Covariance $\mathcal{D} \subset \mathcal{M} \times \mathcal{A} \times \mathcal{F}$

$$\mathcal{L}(f_M^* g, f^* \omega, f^* s) = \mathcal{L}(g, \omega, s), \quad f \in \mathcal{D}\mathcal{M}_x(P)$$

Other: Naturality, Conformal invariance, ...

\rightsquigarrow Principle of gauge invariance

\rightsquigarrow Examples.