

30. The Exponential Map

Version 1.1

Notiztitel

The main tool used to prove several of the results of the last section 29 is the exponential map.

Let G be a Lie group and $X \in T_e G \cong \text{Lie } G$ a tangent vector. The corresponding right invariant vector field $\tilde{X} \in \text{Lie } G \subset \mathcal{D}(G)$ has a flow (cf. section 8)

$$\varphi^{\tilde{X}}(t, a) = \varphi^X(t, a) \quad \text{for } t \in \mathbb{R}, a \in G.$$

$\varphi^{\tilde{X}}(t, a)$ represents \tilde{X} in the sense that $\tilde{X}(a) = [\varphi^X(\cdot, a)]_a$, i.e. the curve $\gamma(t) := \varphi^{\tilde{X}}(t, a)$ satisfies the ordinary differential equation:

$$\dot{\gamma} = \tilde{X}(\gamma).$$

In general, such flows need not be defined for all $t \in \mathbb{R}$, but for the $\tilde{X} \in \text{Lie } G$ this property holds true.

We define

$$\exp X := \varphi^{\tilde{X}}(1, e) \quad \text{and}$$

$$\exp_X(t) := \exp tX := \varphi^{\tilde{X}}(t, e), \quad t \in \mathbb{R}.$$

30-2

(30.1) Lemma: $\varphi_X: \mathbb{R} \rightarrow G$ is a Lie group homomorphism such that $\text{Lie}(\exp_X): \text{Lie } \mathbb{R} \rightarrow \text{Lie } G$, $t \frac{d}{dt} 1 \mapsto tX$.

(30.2) Proposition: The exponential map $\exp: T_e G \rightarrow G$ (or $\exp: \text{Lie } G \rightarrow G$) has the following properties:

$$1^\circ \exp(tX) = \exp_X(t)$$

$$2^\circ \exp(t+s)X = \exp tX \exp sX$$

$$3^\circ \exp(-tX) = (\exp tX)^{-1}$$

4 $^\circ$ \exp is a smooth map and

$$\text{Lie } \exp = T_0 \exp: T_0(T_e G) \rightarrow T_e G$$

is the identity.

5 $^\circ$ \exp is a local diffeomorphism: There is an open $Q \subset T_e G$ such that $\exp(Q) =: U \subset G$ is open and

$$\exp|_Q: Q \rightarrow U$$

is a diffeomorphism.

[13.12.10]

(30.3) Example: For $GL(n, \mathbb{K})$ the exponential map is

$$\exp(X) := e^{tX} = \sum_{n=0}^{\infty} \frac{1}{n!} X^n, \quad X \in \mathfrak{gl}(r, K),$$

the usual exponential series. It is well-known that the series converges. Moreover $\gamma(t) = e^{tX}$ satisfies

$$\dot{\gamma} = X\gamma = \tilde{X}(\gamma).$$

(30.4) DEFINITION: The result 30.2.5° yields special coordinates. Let $Q \subset \mathfrak{g}$ be an open and star shaped neighbourhood of $0 \in \mathfrak{g}$ such the $\exp|_Q : Q \rightarrow \exp(Q) =: U$ is a diffeomorphism (30.2.5°). Then

$$\varphi := (\exp|_Q)^{-1} : U \rightarrow Q \subset \mathfrak{g} = \mathbb{R}^n$$

is a chart. U is called a normal neighbourhood and the coordinates $\varphi = (q^1, \dots, q^n)$ are called normal coordinates.

Correspondingly, we obtain normal neighbourhoods and coordinates around any $g \in G$ by left (or right) translation: $U(g) := \mathcal{L}_g(U)$ and

$$\varphi := \exp^{-1} \circ \mathcal{L}_{g^{-1}} : U(g) \rightarrow Q \subset \mathfrak{g}$$

30-4

(30.5) REMARK: As an example, let us describe how most of the results of the second half of the last section are proven, by establishing 29.8 in the case of $G = GL(n, \mathbb{K})$ (which is all we needed for the construction of $\hat{\mathfrak{g}}$):

Given a Lie subalgebra $\mathfrak{h} \subset \mathfrak{gl}(n, \mathbb{K}) = \mathfrak{g}$ we have to determine a Lie subgroup $H \subset G$ such that $\text{Lie } H = \mathfrak{h}$.

Now, H can be defined by

$$H := \{ e^X : X \in \mathfrak{h} \} = \exp(\mathfrak{h}).$$

Using normal neighbourhoods it is easy to see that H is a submanifold. Moreover, H is a subgroup (and then, of course, the group operations are smooth with respect to the submanifold structure) which follows from the next proposition.

Note, that $\exp(X)\exp(Y) \neq \exp(X+Y)$, in general, but in a normal neighbourhood $U = \exp(Q)$ we have: For $X, Y \in Q$ with $\exp(X+Y) \in U$ there exists a unique $X*Y \in Q$ with

$$\exp(X*Y) = \exp(X+Y).$$

(30.6) PROPOSITION: (Campbell-Hausdorff formula).

$$X * Y = X + Y + \frac{1}{2}[X, Y] - \frac{1}{12}([\![X, Y], X] + [\![Y, X], Y]) + \sum_{k=4}^{\infty} r_k(X, Y)$$

where the r_k are (k -multilinear) expressions in certain combination of Lie brackets where only X, Y are involved.

As a result, $\exp(X+Y)$ differs from $\exp X \exp Y$ only by second order terms, and $X * Y \in \mathfrak{h}$ if $X, Y \in \mathfrak{h}$ for a Lie subalgebra $\mathfrak{h} \subset \mathfrak{g}$.

The exponential mapping is also the key ingredient in the proof of the following structure result:

(30.7) PROPOSITION: A continuous homomorphism between Lie groups is already a Lie group homomorphism.