

INTRODUCTION TO BOHMIAN MECHANICS
SUMMER TERM 2016

EXERCISE SHEET 5

Exercise 1: Spreading of the Wave Packet

A free wave packet is a superposition of plane waves with some weight function:

$$\psi(x, t) = \int f(k) e^{i(kx - \hbar k^2 t / 2m)} dk.$$

Show that this wave function solves the free Schrödinger equation.

Assume that at time $t = 0$, the wave function was given by a Gaussian:

$$\psi(x, t = 0) = N e^{-x^2 / (2\sigma)}.$$

Compute N and discuss the meaning of both N and σ . What are the units of ψ , N and σ ?

For this wave function, what is $f(k)$? What is the group velocity of the wave packet for large σ ?

Now, explicitly compute $\psi(x, t)$ for $t > 0$. Compare your result to $\psi(x, t = 0)$ and discuss.

Compute the trajectory of a Bohmian particle guided by ψ with initial position $X_1(t = 0) = 0$, and that of a Bohmian particle initially at some position $X_2(t = 0) = a > 0$.

Exercise 2: $SO(3)$ and $SU(2)$

Consider the Euclidean scalar product on \mathbb{R}^3 . $SO(3)$ is defined as the group of transformations which leave the scalar product invariant, *i.e.* $SO(3) = \{\sigma : \mathbb{R}^3 \rightarrow \mathbb{R}^3 : \langle x, y \rangle = \langle \sigma x, \sigma y \rangle \forall x, y \in \mathbb{R}^3\}$.

- a) Write $\sigma \in SO(3)$ as a matrix. What conditions do the column (or row) vectors fulfill? How many free entries remain?
- b) Why is the number of free entries consistent with the interpretation of these matrices as rotations?
- c) Why does any $\sigma \in SO(3)$ have at least one real eigenvalue?
- d) Represent $SO(3)$ as the manifold “ball with radius π ” as in the lecture. Why is it not simply connected? Why is the doubly closed path null homotopic?

$SU(2)$ is the set of unitary maps on \mathbb{C}^2 with unit determinant.

- a) What does a generic matrix $\tau \in SU(2)$ look like?
- b) How can you represent $SU(2)$ as a simply connected manifold?
- c) As was shown in the lecture, $SU(2)$ is a cover of $SO(3)$. Which rotation corresponds to

$$\begin{pmatrix} \cos \alpha & i \sin \alpha \\ i \sin \alpha & \cos \alpha \end{pmatrix}?$$

Hint: Recall the representation

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \hat{=} \begin{pmatrix} z & x - iy \\ x + iy & -z \end{pmatrix}.$$

Exercise 3: Ground States

Show that the ground state ψ (with energy e) of a self-adjoint Hamiltonian H can always be chosen as a real function. Proceed along the following steps. You may assume that the ground state wave function is normalised to 1 and the Hamiltonian is of the form $H = -\hbar^2 / (2m) \Delta + V(x)$, where $x \in \mathbb{R}^d$ for some $d > 0$.

- (1) Remind yourself with a simple computation that eigenvalues of self-adjoint operators are always real. The ground state is an eigenfunction of the Hamiltonian, so its energy e (which is just the eigenvalue) is real.
- (2) The most general form for $\psi(x)$ is given by $\psi(x) = R(x) e^{iS(x)}$ with $R \geq 0$ and $S \in \mathbb{R}$. Why?
- (3) Explicitly compute $e = \langle \psi, H\psi \rangle$. Keep in mind that $e \in \mathbb{R}$ and that e is the ground-state energy, *i.e.* for any $\varphi \neq \psi$ it holds that $\langle \varphi, H\varphi \rangle \geq e$. This means that you can freely think about ways to minimise the result of $\langle \psi, H\psi \rangle$.