

Explaining Gentzen's Consistency Proof within Infinitary Proof Theory

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Introduction

There are two main approaches to ordinal analysis of formal theories: the finitary Gentzen-Takeuti approach on one side, and the use of infinitary derivations initiated by Schütte on the other. Up to now these approaches were thought of as separated and only vaguely related. But in the present paper we will show that actually they are intrinsically connected. Using the concept of *notations for infinitary derivations* (introduced in [Bu91]) a precise explanation of Gentzen's reduction steps on derivations in 1st order arithmetic Z (cf. [Ge38]) in terms of (cut-elimination for) infinitary derivations in ω -arithmetic will be given. Even more, Gentzen's reduction steps and ordinal assignment will be *derived* from infinitary proof theory. In a forthcoming paper we will extend the present work to impredicative subsystems of 2nd order arithmetic thereby explaining Takeuti's consistency proof for Π_1^1 -CA in terms of the infinitary approach (with $\Omega_{\mu+1}$ -rules) from [BS88] (cf. [Bu97]).

Our general idea is that such investigations may perhaps be helpful for the understanding and unification of two of the most advanced achievements in contemporary proof theory, namely the methodically quite different work of T. Arai ([Ar96b], [Ar97a], [Ar97b]) and M. Rathjen ([Ra91], [Ra94], [Ra95]) on the ordinal analysis of very strong subsystems of 2nd order arithmetic and set theory.

Content

In §1 and §2 essential material from [Bu91] is repeated in a somewhat modified form, so that it fits exactly for the present purpose. §1 contains the definition of operators \mathcal{R}_C and \mathcal{E} which make up a cut-elimination procedure for \mathbf{Z}^∞ (the infinitary Tait-style sequent calculus for ω -arithmetic) due to Schütte [Sch51], Tait [Ta68] and Mints [Mi75]. In §2 we introduce a finitary Tait-style sequent calculus \mathbf{Z}^* for pure number theory Z which differs from the usual version only by a certain additional inference rule (E) $\frac{\Gamma}{\Gamma}$ and the fact that cuts $\frac{\Gamma, C \quad \Gamma, \neg C}{\Gamma}$ are labeled by the symbol R_C (instead of Cut_C). Every \mathbf{Z}^* -derivation h with closed endsequent is considered as a notation for a certain \mathbf{Z}^∞ -derivation h^∞ of the same sequent. In other words, we define a translation $h \mapsto h^\infty$ from \mathbf{Z}^* into \mathbf{Z}^∞ . The definition of h^∞ runs as usual only that cuts and **E**-inferences are not translated literally but according to the intended meaning of the symbols R_C , **E**:

$$\left(\frac{h_0 \quad h_1}{\Gamma, C \quad \Gamma, \neg C} R_C \right)^\infty := \mathcal{R}_C(h_0^\infty, h_1^\infty), \quad \left(\frac{h_0}{\Gamma} E \right)^\infty := \mathcal{E}(h_0^\infty).$$

From this interpretation and the properties of \mathcal{R}_C and \mathcal{E} (established in §1) one immediately reads off a definition of ordinals $o(h) < \varepsilon_0$ and $\deg(h) < \omega$ such that $\text{depth}(h^\infty) \leq o(h)$ and $\sup\{\text{rk}(C)+1 : C \text{ is cut-formula in } h^\infty\} \leq \deg(h)$. Formally the definition of $o(h)$ and $\deg(h)$ proceeds by (primitive) recursion on the build-up of h and does not refer to h^∞ . Further by looking on the definitions of \mathcal{R}_C and \mathcal{E} (given in §1) we derive (via $h \mapsto h^\infty$) a definition which assigns to each \mathbf{Z}^* -derivation h a certain inference symbol $\text{tp}(h)$ (corresponding to the last inference of h^∞) and, for each $i \in |\text{tp}(h)|$, a new \mathbf{Z}^* -derivation $h[i]$ such that $(h[i])^\infty = h^\infty(i)$, where $(h^\infty(i))_{i \in |\text{tp}(h)|}$ is the family of immediate subderivations of h^∞ . The definition of $\text{tp}(h)$ and $h[i]$ also proceeds by recursion on the build-up of h .

In §3 we describe the (Tait-style adaption of) Gentzen's reduction procedure and ordinal assignment (from [Ge38]) in terms of the notions introduced in §2. Let \mathbf{Z} denote the subsystem of \mathbf{Z}^* obtained by omitting the \mathbf{E} -rule. So \mathbf{Z} is just ordinary 1st order arithmetic. We consider a (hypothetical) \mathbf{Z} -derivation d of the empty sequent. Let d' be the \mathbf{Z}^* -derivation which results from d by filling in \mathbf{E} -inferences in such a way that for each node ν of d' (which originates from a node of d) we have $\text{hgt}^*(d', \nu) = \text{Höhe}(d', \nu)$, where $\text{hgt}^*(d', \nu)$ is the number of \mathbf{E} 's below ν , and Höhe is defined as in [Ge38]. Then $o(d')$ is precisely the ordinal $O(d)$ which Gentzen assigns to d , and $d'[0]$ (after deleting all \mathbf{E} 's) coincides with the result of a Gentzen reduction step applied to d .

Remark. The \mathbf{E} -rule is also present in [Ar96a] (under the name ‘‘height rule’’) but there no interpretation of \mathbf{E} as cut-elimination operator is given.

§1 Cut-elimination for the infinitary system \mathbf{Z}^∞

Preliminaries

We assume a formal language of arithmetic which has predicate symbols for primitive recursive relations, but no function symbols except the constant 0 and the unary function symbol S (successor). *Atomic formulas* are of the form $pt_1 \dots t_n$ where p is an n -ary predicate symbol and t_1, \dots, t_n are terms. *Literals* are expressions of the shape A or $\neg A$ where A is an atomic formula. *Formulas* are built up from literals by means of $\wedge, \vee, \forall x, \exists x$. The *negation* $\neg C$ of a formula C is defined via de Morgan's laws. The *rank* $\text{rk}(C)$ of a formula C is defined as usual: $\text{rk}(C) := 0$ if C is a literal, $\text{rk}(A_0 \wedge A_1) := \text{rk}(A_0 \vee A_1) := \max\{\text{rk}(A_0), \text{rk}(A_1)\} + 1$, $\text{rk}(\forall x A) := \text{rk}(\exists x A) := \text{rk}(A) + 1$. By $\text{FV}(\theta)$ we denote the set of all free variables of the formula or term θ . A formula or term θ is called *closed* iff $\text{FV}(\theta) = \emptyset$. $\theta_x(t)$ (or $\theta(x/t)$) denotes the result of replacing every free occurrence of x in θ by t (renaming bound variables of θ if necessary). The only closed terms are the

numerals $0, S0, SS0, \dots$. We identify numerals and natural numbers. By TRUE_0 we denote the set of all true closed literals. Finite sets of formulas are called *sequents*.

We use the following syntactic variables: s, t for terms, A, B, C, D, F for formulas, Γ, Δ for sequents, α, β, γ for ordinals, i, j, k, l, m, n for natural numbers (and numerals).

As far as sequents are concerned we usually write A_1, \dots, A_n for $\{A_1, \dots, A_n\}$, and A, Γ, Δ for $\{A\} \cup \Gamma \cup \Delta$, etc.

Proof systems

A *proof system* \mathfrak{S} is given by

- a set of formal expressions called *inference symbols* (syntactic variable \mathcal{I})
- for each inference symbol \mathcal{I} a set $|\mathcal{I}|$, a sequent $\Delta(\mathcal{I})$ and a family of sequents $(\Delta_\iota(\mathcal{I}))_{\iota \in |\mathcal{I}|}$.

NOTATION

By writing $(\mathcal{I}) \frac{\dots \Delta_\iota \dots (\iota \in I)}{\Delta}$

we declare \mathcal{I} as an inference symbol with $|\mathcal{I}| = I$, $\Delta(\mathcal{I}) = \Delta$, $\Delta_\iota(\mathcal{I}) = \Delta_\iota$.

If $|\mathcal{I}| = \{0, \dots, n-1\}$ we write $\frac{\Delta_0 \ \Delta_1 \ \dots \ \Delta_{n-1}}{\Delta}$ instead of $\frac{\dots \Delta_\iota \dots (\iota \in I)}{\Delta}$.

Up to a few exceptions the sequents $\Delta(\mathcal{I}), \Delta_\iota(\mathcal{I})$ are singletons or empty.

Definition

The figure $\frac{\dots \Gamma_\iota \dots (\iota \in I)}{\Gamma} \mathcal{I}$ is called a (*correct*) \mathfrak{S} -*inference* iff

$\mathcal{I} \in \mathfrak{S}$ and $|\mathcal{I}| = I$ and $\Delta(\mathcal{I}) \subseteq \Gamma$ and $\forall \iota \in I (\Gamma_\iota \subseteq \Gamma, \Delta_\iota(\mathcal{I}))$.

The infinitary proof system \mathbf{Z}^∞ (ω -arithmetic)

(Ax_A) $\frac{}{A}$ if $A \in \text{TRUE}_0$.

($\wedge_{A_0 \wedge A_1}$) $\frac{A_0 \quad A_1}{A_0 \wedge A_1}$ ($\vee_{A_0 \vee A_1}^k$) $\frac{A_k}{A_0 \vee A_1}$ ($k \in \{0, 1\}$)

($\wedge_{\forall x A}$) $\frac{\dots A_x(i) \dots (i \in \mathbb{N})}{\forall x A}$ ($\vee_{\exists x A}^k$) $\frac{A_x(k)}{\exists x A}$ ($k \in \mathbb{N}$)

(Cut_C) $\frac{C \quad \neg C}{\emptyset}$ (Rep) $\frac{\emptyset}{\emptyset}$

Note:

To avoid a possible misunderstanding we stress that $|\text{Rep}| = \{0\}$ while $|\text{Ax}_A| = \emptyset$.

Inductive definition of \mathbf{Z}^∞ -derivations

If Γ is a sequent, α an ordinal, $\mathcal{I} \in \mathbf{Z}^\infty$, and $(\mathbf{d}_i)_{i \in I}$ a family of \mathbf{Z}^∞ -derivations

such that $\frac{\dots \Gamma(\mathbf{d}_i) \dots (i \in I)}{\Gamma} \mathcal{I}$ is a correct \mathbf{Z}^∞ -inference and $\forall i \in I (o(\mathbf{d}_i) < \alpha)$

then the tree $\mathbf{d} := \frac{\dots \mathbf{d}_i \dots (i \in I)}{\mathcal{I} : \Gamma : \alpha}$ is a \mathbf{Z}^∞ -derivation with

$\Gamma(\mathbf{d}) := \Gamma$, $\text{last}(\mathbf{d}) := \mathcal{I}$, $\text{o}(\mathbf{d}) := \alpha$, $\mathbf{d}(i) := \mathbf{d}_i$

and $\text{deg}(\mathbf{d}) := \begin{cases} \max\{\text{rk}(C)+1, \text{deg}(\mathbf{d}_0), \text{deg}(\mathbf{d}_1)\} & \text{if } \mathcal{I} = \text{Cut}_C \\ \sup\{\text{deg}(\mathbf{d}_i) : i \in I\} & \text{otherwise} \end{cases}$

$\Gamma(\mathbf{d})$ is called the *endsequent* of \mathbf{d} , $\text{o}(\mathbf{d})$ the *ordinal* of \mathbf{d} , $\text{last}(\mathbf{d})$ the *last inference (symbol)* of \mathbf{d} , and $\mathbf{d}(i)$ the *i -th immediate subderivation* of \mathbf{d} .

We use $\mathbf{d}, \mathbf{d}_0, \dots$ as syntactic variables for \mathbf{Z}^∞ -derivations.

Abbreviation $\mathbf{d} \vdash_m^\alpha \Gamma : \iff \Gamma(\mathbf{d}) \subseteq \Gamma \ \& \ \text{deg}(\mathbf{d}) \leq m \ \& \ \text{o}(\mathbf{d}) = \alpha$.

Cut-elimination for \mathbf{Z}^∞

Theorem 1 and Definition

Let C be given. We define an operator \mathcal{R}_C such that:

$\mathbf{d}_0 \vdash_m^\alpha \Gamma, C \ \& \ \mathbf{d}_1 \vdash_m^\beta \Gamma, \neg C \ \& \ \text{rk}(C) \leq m \implies \mathcal{R}_C(\mathbf{d}_0, \mathbf{d}_1) \vdash_m^{\alpha\#\beta} \Gamma$.

Proof by induction on $\alpha\#\beta$:

W.l.o.g. we may assume that $\Gamma = (\Gamma(\mathbf{d}_0) \setminus \{C\}) \cup (\Gamma(\mathbf{d}_1) \setminus \{\neg C\})$.

Case 1. $C \notin \Delta(\mathcal{I})$ where $\mathcal{I} := \text{last}(\mathbf{d}_0)$:

Then $\Delta(\mathcal{I}) \subseteq \Gamma$, and $\mathbf{d}_0(i) \vdash_m^{\alpha_i} \Gamma, C, \Delta_i(\mathcal{I})$ with $\alpha_i < \alpha$, for all $i \in |\mathcal{I}|$.

By IH we get $\mathcal{R}_C(\mathbf{d}_0(i), \mathbf{d}_1) \vdash_m^{\alpha_i\#\beta} \Gamma, \Delta_i(\mathcal{I})$ for all $i \in |\mathcal{I}|$.

Hence $\mathcal{R}_C(\mathbf{d}_0, \mathbf{d}_1) := \frac{\dots \mathcal{R}_C(\mathbf{d}_0(i), \mathbf{d}_1) \dots (i \in |\mathcal{I}|)}{\mathcal{I} : \Gamma : \alpha\#\beta}$ is a derivation as required.

Case 1'. $\neg C \notin \Delta(\text{last}(\mathbf{d}_1))$: symmetric to Case 1.

Case 2. $C \in \Delta(\text{last}(\mathbf{d}_0))$ and $\neg C \in \Delta(\text{last}(\mathbf{d}_1))$:

Then $\text{rk}(C) \neq 0$, since C and $\neg C$ cannot both be true literals.

Case 2.1. $C = \forall x A(x)$: Then $\neg C = \exists x \neg A(x)$, $\text{last}(\mathbf{d}_1) = \bigvee_{-C}^k$, and

$\mathbf{d}_0(i) \vdash_m^{\alpha_i} \Gamma, C, A(i)$ with $\alpha_i < \alpha$, for all $i \in \mathbb{N}$,

$\mathbf{d}_1(0) \vdash_m^{\beta_0} \Gamma, C, \neg A(k)$ with $\beta_0 < \beta$.

By IH we get $\mathcal{R}_C(\mathbf{d}_0(k), \mathbf{d}_1) \vdash_m^{\alpha_k\#\beta} \Gamma, A(k)$ and $\mathcal{R}_C(\mathbf{d}_0, \mathbf{d}_1(0)) \vdash_m^{\alpha\#\beta_0} \Gamma, \neg A(k)$.

Further $\text{rk}(A(k)) < \text{rk}(C) \leq m$.

Hence $\mathcal{R}_C(\mathbf{d}_0, \mathbf{d}_1) := \frac{\mathcal{R}_C(\mathbf{d}_0(k), \mathbf{d}_1) \quad \mathcal{R}_C(\mathbf{d}_0, \mathbf{d}_1(0))}{\text{Cut}_{A(k)} : \Gamma : \alpha\#\beta}$.

Case 2.2.-2.4. $C = \exists x A$ or $A_0 \wedge A_1$ or $A_0 \vee A_1$: analogous to Case 2.1.

Theorem 2 and Definition

We define an operator \mathcal{E} such that: $\mathbf{d} \vdash_{m+1}^\alpha \Gamma \implies \mathcal{E}(\mathbf{d}) \vdash_m^{\omega^\alpha} \Gamma$.

Proof by induction on α :

W.l.o.g. we may assume that $\Gamma = \Gamma(\mathbf{d})$.

Case 1. $\text{last}(\mathbf{d}) = \text{Cut}_C$:

Then $\text{rk}(C) \leq m$ and $\mathbf{d}(0) \vdash_{m+1}^{\alpha_0} \Gamma, C$, $\mathbf{d}(1) \vdash_{m+1}^{\alpha_1} \Gamma, \neg C$ with $\alpha_0, \alpha_1 < \alpha$.

By IH we get $\mathcal{E}(\mathbf{d}(0)) \vdash_m^{\omega^{\alpha_0}} \Gamma, C$ and $\mathcal{E}(\mathbf{d}(1)) \vdash_m^{\omega^{\alpha_1}} \Gamma, \neg C$.

Hence by Theorem 1 $\mathcal{R}_C(\mathcal{E}(d(0)), \mathcal{E}(d(1))) \vdash_m^{\omega^{\alpha_0} \# \omega^{\alpha_1}} \Gamma$, and

$\mathcal{E}(d) := \left\{ \frac{\mathcal{R}_C(\mathcal{E}(d(0)), \mathcal{E}(d(1)))}{\text{Rep} : \Gamma : \omega^\alpha} \right\}$ is a derivation as required.

Case 2. otherwise: $\mathcal{E}(d) := \left\{ \frac{\dots \mathcal{E}(d(i)) \dots (i \in |\mathcal{I}|)}{\mathcal{I} : \Gamma : \omega^\alpha} \right\}$ where $\mathcal{I} := \text{last}(d)$.

Remark In the whole paper $\lambda\xi.\omega^\xi$ could be replaced by any ordinal function f such that $\forall \alpha_0, \alpha_1, \alpha(\alpha_0, \alpha_1 < \alpha \Rightarrow f(\alpha_0) \# f(\alpha_1) < f(\alpha))$.

§2 The finitary system \mathbf{Z}^*

Let Z be the formal system of pure number theory (Peano arithmetic). The mathematical axioms of Z are the scheme of complete induction and finitely many axioms of the shape $\forall \vec{x}(A_0 \vee \dots \vee A_m)$ where A_0, \dots, A_m are literals. In our sequent calculus the latter axioms are represented by a (prim. rec.) set $\text{Ax}(Z)$ of sequents such that

- (i) $\Delta \in \text{Ax}(Z) \ \& \ A \in \Delta \Rightarrow A$ is a literal,
- (ii) $\Delta \in \text{Ax}(Z) \Rightarrow \Delta_{\vec{x}}(\vec{t}) \in \text{Ax}(Z)$,
- (iii) $\Delta \in \text{Ax}(Z) \ \& \ \text{FV}(\Delta) = \emptyset \Rightarrow \Delta \cap \text{TRUE}_0 \neq \emptyset$.

Definition of the finitary proof system \mathbf{Z}^*

The inference symbols of \mathbf{Z}^* are

$$\begin{aligned} (\text{Ax}_\Delta) \quad & \frac{}{\Delta} \text{ if } \Delta \in \text{Ax}(Z), \quad (\wedge_{\forall x A}^y) \quad \frac{A_x(y)}{\forall x A}, \quad (\vee_{\exists x A}^t) \quad \frac{A_x(t)}{\exists x A}, \\ (\text{Ind}_F^{y,t}) \quad & \frac{\neg F, F_y(Sy)}{\neg F_y(0), F_y(t)}, \quad (\text{R}_C) \quad \frac{C}{\emptyset} \frac{\neg C}{\emptyset}, \quad (\text{E}) \quad \frac{\emptyset}{\emptyset}, \end{aligned}$$

and $\wedge_{A_0 \wedge A_1}^k, \vee_{A_0 \vee A_1}^k$ as in \mathbf{Z}^∞ .

\mathbf{Z}^* -derivations

\mathbf{Z}^* -derivations are defined in a somewhat different style than \mathbf{Z}^∞ -derivations. The difference is that the nodes of a \mathbf{Z}^* -derivation h are labeled with inference symbols only, while the endsequent $\Gamma(h)$ and the ordinal $\text{o}(h)$ of h will be computed from h by structural recursion. Actually \mathbf{Z}^* -derivations will be introduced as *terms* (in prefix notation) built up from inference symbols \mathcal{I} which we consider as n -ary function symbols, where $|\mathcal{I}| = \{0, \dots, n-1\}$.

Inductive Definition of \mathbf{Z}^* -quasi-derivations

If \mathcal{I} is an n -ary \mathbf{Z}^* -inference symbol and h_0, \dots, h_{n-1} are \mathbf{Z}^* -quasi-derivations then $h := \mathcal{I}h_0 \dots h_{n-1}$ is a \mathbf{Z}^* -quasi-derivation and

$$\begin{aligned} \Gamma(h) &:= \Delta(\mathcal{I}) \cup \bigcup_{i < n} (\Gamma(h_i) \setminus \Delta_i(\mathcal{I})), \\ \text{o}(h) &:= \begin{cases} \text{o}(h_0) \# \text{o}(h_1) & \text{if } \mathcal{I} = \text{R}_C \\ \text{o}(h_0) \cdot \omega & \text{if } \mathcal{I} = \text{Ind}_F^{y,t} \\ \omega^{\text{o}(h_0)} & \text{if } \mathcal{I} = \text{E} \\ (\sup_{i < n} \text{o}(h_i)) + 1 & \text{otherwise} \end{cases}, \end{aligned}$$

$$\deg(h) = \begin{cases} \max\{\text{rk}(C), \deg(h_0), \deg(h_1)\} & \text{if } \mathcal{I} = \text{R}_C \\ \max\{\text{rk}(F), \deg(h_0)\} & \text{if } \mathcal{I} = \text{Ind}_F^{y,t} \\ \deg(h_0) \dot{-} 1 & \text{if } \mathcal{I} = \text{E} \\ \sup_{i < n} \deg(h_i) & \text{otherwise} \end{cases}$$

Remark: The definitions of $\text{o}(h)$ and $\deg(h)$ are motivated by the interpretation $h \mapsto h^\infty$ (introduced below) and Theorems 1,2.

Inductive Definition of \mathbf{Z}^* -derivations

If \mathcal{I} is an n -ary \mathbf{Z}^* -inference symbol and h_0, \dots, h_{n-1} are \mathbf{Z}^* -derivations then $h := \mathcal{I}h_0 \dots h_{n-1}$ is a \mathbf{Z}^* -derivation if the following conditions are satisfied

- $\mathcal{I} = \bigwedge_{\forall x A}^y \Rightarrow y \notin \text{FV}(\Gamma(h))$,
- $\mathcal{I} = \text{Ind}_F^{y,t} \Rightarrow y \notin \text{FV}(\Gamma(h))$,
- $\mathcal{I} = \bigvee_{\exists x A}^t \Rightarrow \text{FV}(t) \subseteq \text{FV}(\Gamma(h))$,
- $\mathcal{I} = \text{R}_C \Rightarrow \text{FV}(C) \subseteq \text{FV}(\Gamma(h))$.

A \mathbf{Z}^* -derivation h is called *closed* iff $\text{FV}(\Gamma(h)) = \emptyset$.

Remark: As one easily verifies the last two conditions in the above definition do not restrict the set of provable sequents. They imply the following proposition:

If $h = \mathcal{I}h_0 \dots h_{n-1}$ is a closed \mathbf{Z}^* -derivation with $\mathcal{I} \neq \bigwedge_{\forall x A}^y, \text{Ind}_F^{y,t}$ then h_0, \dots, h_{n-1} are closed too. If $h = \bigwedge_{\forall x A}^y h_0$ or $h = \text{Ind}_F^{y,t} h_0$ is closed then $\text{FV}(\Gamma(h_0)) \subseteq \{y\}$.

Definition

Let \mathbf{Z} denote the subsystem of \mathbf{Z}^* which arises by omitting the symbol E . Obviously \mathbf{Z} is nothing else than the Tait-style version of pure number theory Z .

We use d, d_i (h, h_i) as syntactic variables for $\mathbf{Z}(\mathbf{Z}^*)$ -derivations.

Definition

In the usual way we define $h(z/i)$, i.e. the result of substituting i for z in h :

$$\text{Ax}_\Delta(z/i) := \text{Ax}_{\Delta_z(i)},$$

$$(\bigvee_C^t h_0)(z/i) := \bigvee_{C_z(i)}^{t_z(i)} h_0(z/i), (\bigwedge_C h_0 h_1)(z/i) := \bigwedge_{C_z(i)} h_0(z/i) h_1(z/i),$$

$$(\bigwedge_C^z h_0)(z/i) := \bigwedge_C^z h_0, (\bigwedge_C^y h_0)(z/i) := \bigwedge_{C_z(i)}^y h_0(z/i) \text{ if } y \neq z,$$

$$(\text{Ind}_F^{z,t} h_0)(z/i) := \text{Ind}_F^{z,t} h_0, (\text{Ind}_F^{y,t} h_0)(z/i) := \text{Ind}_{F_z(i)}^{y,t_z(i)} h_0(z/i) \text{ if } y \neq z,$$

$$(\text{R}_C h_0 h_1)(z/i) := \text{R}_{C_z(i)} h_0(z/i) h_1(z/i), (\text{E}h_0)(z/i) := \text{E}h_0(z/i).$$

Proposition If h is a \mathbf{Z}^* -derivation then also $h(z/i)$ is a \mathbf{Z}^* -derivation and $\Gamma(h(z/i)) \subseteq \Gamma(h)_z(i)$, $\deg(h(z/i)) = \deg(h)$, $\text{o}(h(z/i)) = \text{o}(h)$.

Interpretation of \mathbf{Z}^* in \mathbf{Z}^∞

For each closed \mathbf{Z}^* -derivation h we define its interpretation $h^\infty \in \mathbf{Z}^\infty$ as follows:

Let $h = \mathcal{I}h_0 \dots h_{n-1}$, $\Gamma = \Gamma(h)$, $\alpha = \text{o}(h)$:

0. $(\text{Ax}_\Gamma)^\infty := \left\{ \frac{}{\text{Ax}_A : \Gamma : \alpha} \right\}$, where A is the “least” element of $\Gamma \cap \text{TRUE}_0$,
1. $(\bigwedge_{\forall x A}^y h_0)^\infty := \left\{ \frac{\dots h_0(y/i)^\infty \dots (i \in \mathbb{N})}{\bigwedge_{\forall x A} : \Gamma : \alpha} \right\}$,

2. $(R_C h_0 h_1)^\infty := \mathcal{R}_C(h_0^\infty, h_1^\infty)$,
3. $(E h_0)^\infty := \mathcal{E}(h_0^\infty)$,
4. $(\text{Ind}_F^{y,n} h_0)^\infty := \left\{ \frac{e_n}{\text{Rep} : \Gamma : \alpha} \right.$ with
 $e_1 := h_0(y/0)^\infty$, $e_{i+1} := \mathcal{R}_{F(i)}(e_i, h_0(y/i)^\infty)$ for $i > 0$, and e_0 is the canonical \mathbf{Z}^∞ -derivation with $\Gamma(e_0) = \{\neg F(0), F(0)\}$, $\text{deg}(e_0) = 0$, $\text{o}(e_0) = 2\text{rk}(F)$.
5. Otherwise: $(I h_0 \dots h_{n-1})^\infty := \left\{ \frac{h_0^\infty \dots h_{n-1}^\infty}{\mathcal{I} : \Gamma : \alpha} \right.$

Remark With the help of Theorems 1,2 one easily verifies that h^∞ is a \mathbf{Z}^∞ -derivation with $h^\infty \vdash_{\text{deg}(h)}^{\text{o}(h)} \Gamma(h)$.

Definition of $\text{tp}(h)$ and $h[i]$ for closed \mathbf{Z}^* -derivations h and $i \in |\text{tp}(h)|$

By (prim.) recursion on the build-up of h we define an inference symbol $\text{tp}(h) \in \mathbf{Z}^\infty$ and closed \mathbf{Z}^* -derivation(s) $h[i]$ in such a way that $\text{tp}(h) = \text{last}(h^\infty)$ and $(h[i])^\infty = h^\infty(i)$. The definition clauses for $h = R_C h_0 h_1$ and $h = E h_0$ can be read off from the corresponding clauses in the definitions of \mathcal{R}_C and \mathcal{E} .

- 1.1. $h = \text{Ax}_\Delta$: $\text{tp}(\text{Ax}_\Delta) := \text{Ax}_A$ where A is the “least” element of $\Delta \cap \text{TRUE}_0$.
- 1.2. $h = \bigwedge_C h_0 h_1$: $\text{tp}(h) := \bigwedge_C$, $h[i] := h_i$.
- 1.3. $h = \bigwedge_C^y h_0$: $\text{tp}(h) := \bigwedge_C$, $h[i] := h_0(y/i)$.
- 1.4. $h = \bigvee_C^k h_0$: $\text{tp}(h) := \bigvee_C^k$, $h[0] := h_0$.
2. $h = \text{Ind}_F^{y,n} h_0$: $\text{tp}(h) := \text{Rep}$, $h[0] := e_n$ with
 $e_1 := h_0(y/0)$, $e_{i+1} := \mathcal{R}_{F(i)} e_i h_0(y/i)$ for $i > 0$, and e_0 is the canonical \mathbf{Z} -derivation with $\Gamma(e_0) = \{\neg F(0), F(0)\}$, $\text{deg}(e_0) = 0$, $\text{o}(e_0) = 1 + 2\text{rk}(F)$.
3. $h = E h_0$:
 - 3.1. $\text{tp}(h_0) = \text{Cut}_C$: $\text{tp}(h) := \text{Rep}$, $h[0] := R_C E h_0[0] E h_0[1]$,
 - 3.2. otherwise: $\text{tp}(h) := \text{tp}(h_0)$, $h[i] := E h_0[i]$.
4. $h = R_C h_0 h_1$:
 - 4.1. $C \notin \Delta(\text{tp}(h_0))$: $\text{tp}(h) := \text{tp}(h_0)$, $h[i] := R_C h_0[i] h_1$.
 - 4.2. $\neg C \notin \Delta(\text{tp}(h_1))$: $\text{tp}(h) := \text{tp}(h_1)$, $h[i] := R_C h_0 h_1[i]$.
 - 4.3. $C \in \Delta(\text{tp}(h_0))$ and $\neg C \in \Delta(\text{tp}(h_1))$:
Then $\text{rk}(C) \neq 0$, since C and $\neg C$ cannot both be true literals.
 - 4.3.1. $C = \forall x A$: Then $\text{tp}(h_1) = \bigvee_{\neg C}^k$ for some $k \in \mathbb{N}$.
 $\text{tp}(h) := \text{Cut}_{A_x(k)}$, $h[0] := R_C h_0[k] h_1$, $h[1] := R_C h_0 h_1[0]$.
 - 4.3.2. $C = \exists x A$ or $A_0 \wedge A_1$ or $A_0 \vee A_1$: analogous to 4.3.1.

Theorem 3

For each closed \mathbf{Z}^* -derivation h the following holds:

- a) $\frac{\dots \Gamma(h[i]) \dots (i \in |\text{tp}(h)|)}{\Gamma(h)} \text{tp}(h)$ is a correct \mathbf{Z}^∞ -inference,
- b) $\text{tp}(h) = \text{Cut}_C \Rightarrow \text{rk}(C) < \text{deg}(h)$,

- c) $\deg(h[i]) \leq \deg(h)$ for all $i \in |\text{tp}(h)|$,
d) $o(h[i]) < o(h)$ for all $i \in |\text{tp}(h)|$.

Proof by straightforward induction on the build-up of h :

We only consider two cases.

Abbreviation: $h \vdash_m^\alpha \Gamma := \Gamma(h) \subseteq \Gamma \ \& \ \deg(h) \leq m \ \& \ o(h) = \alpha$.

1. $h = \text{R}_C h_0 h_1$ with $C = \forall x A$, $\text{tp}(h_0) = \bigwedge_C$, $\text{tp}(h_1) = \bigvee_{-C}^k$, $\text{tp}(h) = \text{Cut}_{A(k)}$:

Let $\Gamma := \Gamma(h)$, $\alpha := o(h_0)$, $\beta := o(h_1)$, and $m := \deg(h)$.

Then $h_0 \vdash_m^\alpha \Gamma, C$ and $h_1 \vdash_m^\beta \Gamma, \neg C$ and $\text{rk}(A(k)) < \text{rk}(C) \leq \deg(h)$.

By IH we obtain $h_0[k] \vdash_m^{\alpha_k} \Gamma, C, A(k)$ with $\alpha_k < \alpha$,

and $h_1[0] \vdash_m^{\beta_0} \Gamma, \neg C, \neg A(k)$ with $\beta_0 < \beta$.

Hence $h[0] = \text{R}_C h_0[k] h_1 \vdash_m^{\alpha_k \# \beta} \Gamma, A(k)$ and $h[1] = \text{R}_C h_0 h_1[0] \vdash_m^{\alpha \# \beta_0} \Gamma, \neg A(k)$
with $\alpha_k \# \beta$, $\alpha \# \beta_0 < \alpha \# \beta = o(h)$.

2. $h = \text{E}h_0$ with $\text{tp}(h_0) = \text{Cut}_C$: Then $\text{tp}(h) = \text{Rep}$ and $h[0] = \text{R}_C \text{E}h_0[0] \text{E}h_0[1]$.

Let $\Gamma := \Gamma(h_0) = \Gamma(h)$, $\alpha := o(h_0)$ and $m := \deg(h_0) - 1 = \deg(h)$.

By IH we have $\text{rk}(C) < \deg(h_0) \leq m+1$ and $h_0[0] \vdash_{m+1}^{\alpha_0} \Gamma, C$, $h_0[1] \vdash_{m+1}^{\alpha_1} \Gamma, \neg C$
with $\alpha_0, \alpha_1 < \alpha$. Hence $\text{E}h_0[0] \vdash_m^{\omega^{\alpha_0}} \Gamma, C$ and $\text{E}h_0[1] \vdash_m^{\omega^{\alpha_1}} \Gamma, \neg C$.

From this together with $\text{rk}(C) \leq m$ we get $h[0] = \text{R}_C \text{E}h_0[0] \text{E}h_0[1] \vdash_m^{\omega^{\alpha_0} \# \omega^{\alpha_1}} \Gamma$
and $\omega^{\alpha_0} \# \omega^{\alpha_1} < \omega^\alpha = o(h)$.

Corollary

Let \mathbf{Z}_\perp^* be the set of all \mathbf{Z}^* -derivations h with $\Gamma(h) = \emptyset$ & $\deg(h) = 0$.

- a) $h \in \mathbf{Z}_\perp^* \Rightarrow h[0] \in \mathbf{Z}_\perp^*$ & $o(h[0]) < o(h)$,
b) There is no \mathbf{Z} -derivation d with $\Gamma(d) = \emptyset$.

Proof:

a) $h \in \mathbf{Z}_\perp^* \xrightarrow{\text{Th.3}} h \in \mathbf{Z}_\perp^*$ & $\text{tp}(d) = \text{Rep} \xrightarrow{\text{Th.3}} h[0] \in \mathbf{Z}_\perp^*$ & $o(h[0]) < o(h)$.

b) By transfinite induction up to ε_0 from a) we get $\mathbf{Z}_\perp^* = \emptyset$. Now assume that
 d is a \mathbf{Z} -derivation with $\Gamma(d) = \emptyset$. Let $m := \deg(d)$. Then $\text{E}^m d = \text{E} \dots \text{E} d \in \mathbf{Z}_\perp^*$.
Contradiction.

Conclusion

In this section we have proved the consistency of \mathbf{Z} in a Gentzen style manner (i.e., by defining reduction steps on finite derivations in such a way that the assigned ordinals decrease), but we have not yet achieved a literal reconstruction of Gentzen's original consistency proof in [Ge38]. This is contained in §3.

§3 Connection to Gentzen's consistency proof

Notation:

If d is a \mathbf{Z} -derivation and ν a node (position) in d then :

- (i) $d|_\nu$ denotes the subderivation of d determined by ν . (Especially $d|_{\langle \rangle} = d$)
(ii) $\text{hgt}(d, \nu)$ is Gentzen's height (Höhe) of ν in d .
(iii) $O(d, \nu)$ is the ordinal which Gentzen assigns to ν in d .

(The definition of $\text{hgt}(d, \nu)$ and $O(d, \nu)$ can be found in the proof of Lemma 1.)

Definition

For each \mathbf{Z}^* -derivation h let $\phi(h)$ denote the \mathbf{Z} -derivation which results from h by deleting all \mathbf{E} 's.

Definition of a \mathbf{Z}^* -derivation $\psi_n(d)$ for each \mathbf{Z} -derivation d

1. $\psi_n(\mathbf{R}_C d_0 d_1) := \mathbf{E}^{l-n} \mathbf{R}_C \psi_l(d_0) \psi_l(d_1)$, where $l := \max\{n, \text{rk}(C)\}$,
2. $\psi_n(\text{Ind}_F^{y,t} d_0) := \mathbf{E}^{l-n} \text{Ind}_F^{y,t} \psi_l(d_0)$, where $l := \max\{n, \text{rk}(F)\}$,
3. Otherwise: $\psi_n(\mathcal{I}d_0 \dots d_{m-1}) := \mathcal{I}\psi_n(d_0) \dots \psi_n(d_{m-1})$.

Proposition

$\Gamma(\psi_n(d)) = \Gamma(d)$, $\deg(\psi_n(d)) \leq n$, $\phi(\psi_n(d)) = d$.

Remark

As we will see below (cf. Lemma 5) $\psi_n(d)$ has the following minimality property:
 $\forall h (\deg(h) \leq n \ \& \ \phi(h) = d \Rightarrow o(\psi_n(d)) \leq o(h))$.

The rest of this section is occupied with the proof of the following Theorem.

Theorem 4

For each \mathbf{Z} -derivation d we have

- a) $o(\psi_0(d)) = O(d, \langle \rangle)$.
- b) If $\Gamma(d) = \emptyset$ then $\text{red}(d) := \phi(\psi_0(d)[0])$ results from d by a Gentzen reduction step, and $O(\text{red}(d), \langle \rangle) < O(d, \langle \rangle)$.

Lemma 1

If $n = \text{hgt}(d, \nu)$ then $o(\psi_n(d|_\nu)) = O(d, \nu)$.

Proof by induction on $d|_\nu$:

1. $d|_\nu = \mathbf{R}_C d_0 d_1$: Then $d_i = d|_{\nu * \langle i \rangle}$ and $\text{hgt}(d, \nu * \langle i \rangle) = l := \max\{n, \text{rk}(C)\}$. Hence by IH $o(\psi_l(d_i)) = O(d, \nu * \langle i \rangle)$, and thus $o(\psi_n(d|_\nu)) = \omega_{l-n}(o(\psi_l(d_0)) \# o(\psi_l(d_1))) = \omega_{l-n}(O(d, \nu * \langle 0 \rangle) \# O(d, \nu * \langle 1 \rangle)) = O(d, \nu)$.
2. $d|_\nu = \text{Ind}_F^{y,t} d_0$: Then $d_0 = d|_{\nu * \langle 0 \rangle}$ and $\text{hgt}(d, \nu * \langle 0 \rangle) = l := \max\{n, \text{rk}(F)\}$. Hence $o(\psi_n(d|_\nu)) = \omega_{l-n}(o(\psi_l(d_0)) \cdot \omega) \stackrel{\text{IH}}{=} \omega_{l-n}(O(d, \nu * \langle 0 \rangle) \cdot \omega) = O(d, \nu)$.
3. $d|_\nu = \mathcal{I}d_0 \dots d_{k-1}$ otherwise: Then $d_i = d|_{\nu * \langle i \rangle}$ and $\text{hgt}(d, \nu * \langle i \rangle) = n$. Hence by IH $o(\psi_n(d_i)) = O(d, \nu * \langle i \rangle)$ and thus $o(\psi_n(d|_\nu)) = (\sup_{i < k} o(\psi_n(d_i))) + 1 = (\sup_{i < k} O(d, \nu * \langle i \rangle)) + 1 = O(d, \nu)$.

From Lemma 1 we get $o(\psi_0(d|_\langle \rangle)) = O(d, \langle \rangle)$, and thus Theorem 4a is proved.

Abbreviation: $\mathbf{E}^m h := \underbrace{\mathbf{E} \dots \mathbf{E}}_m h$.

Definition (Nominal forms for derivations)

1. $*$ is a nominal form. $\text{Cut}(*) := \emptyset$, $\text{hgt}^*(*) := 0$.
2. If \mathbf{a} is a nominal form, $m \in \mathbb{N}$, and h a \mathbf{Z}^* -derivation then $\mathbf{E}^m \mathbf{R}_C \mathbf{a} h$ and $\mathbf{E}^m \mathbf{R}_C h \mathbf{a}$ are nominal forms.
 $\text{Cut}(\mathbf{E}^m \mathbf{R}_C \mathbf{a} h) := \text{Cut}(\mathbf{a}) \cup \{C\}$, $\text{Cut}(\mathbf{E}^m \mathbf{R}_C h \mathbf{a}) := \text{Cut}(\mathbf{a}) \cup \{-C\}$,
 $\text{hgt}^*(\mathbf{E}^m \mathbf{R}_C \mathbf{a} h) := \text{hgt}^*(\mathbf{E}^m \mathbf{R}_C h \mathbf{a}) := m + \text{hgt}^*(\mathbf{a})$.

We use $\mathbf{a}, \mathbf{b}, \mathbf{c}$ as syntactic variables for nominal forms.

Definition

$\text{hgt}(\mathbf{a}) := \sup\{\text{rk}(C) : C \in \text{Cut}(\mathbf{a})\},$

$\mathbf{a}\{q\} :=$ the result of substituting q for $*$ in \mathbf{a} (q a nominal form or \mathbf{Z}^* -derivation).

Lemma 2

$\psi_n(d) = \mathbf{a}\{h'\} \Rightarrow n + \text{hgt}^*(\mathbf{a}) = \max\{n, \text{hgt}(\mathbf{a})\}.$

Proof by induction on \mathbf{a} :

1. $\mathbf{a} = *:$ $n + \text{hgt}^*(\mathbf{a}) = n = \max\{n, \text{hgt}(\mathbf{a})\}.$

2. $\mathbf{a} = \mathbf{E}^m \mathbf{R}_C \mathbf{a}_0 h_1:$

Then $d = \mathbf{R}_C d_0 d_1$ and $\psi_n(d) = \mathbf{E}^{l-n} \mathbf{R}_C \psi_l(d_0) \psi_l(d_1)$ with $l := \max\{\text{rk}(C), n\}.$

This yields $\mathbf{E}^m \mathbf{R}_C \mathbf{a}_0 \{h'\} h_1 = \mathbf{a}\{h'\} = \mathbf{E}^{l-n} \mathbf{R}_C \psi_l(d_0) \psi_l(d_1)$ and then $m = l - n$

and $\mathbf{a}_0 \{h'\} = \psi_l(d_0)$. Hence $n + \text{hgt}^*(\mathbf{a}) = l + \text{hgt}^*(\mathbf{a}_0) \stackrel{\text{IH}}{=} \max\{l, \text{hgt}(\mathbf{a}_0)\} = \max\{n, \text{rk}(C), \text{hgt}(\mathbf{a}_0)\} = \max\{n, \text{hgt}(\mathbf{a})\}.$

Corollary

$\psi_0(d) = \mathbf{a}\{\mathbf{b}\{h'\}\} \Rightarrow \text{hgt}(\mathbf{a}\{\mathbf{b}\}) = \text{hgt}(\mathbf{a}) + \text{hgt}^*(\mathbf{b}).$

Proof: $\text{hgt}(\mathbf{a}\{\mathbf{b}\}) \stackrel{\text{L.2}}{=} \text{hgt}^*(\mathbf{a}\{\mathbf{b}\}) = \text{hgt}^*(\mathbf{a}) + \text{hgt}^*(\mathbf{b}) \stackrel{\text{L.2}}{=} \text{hgt}(\mathbf{a}) + \text{hgt}^*(\mathbf{b})$

Definition

A \mathbf{Z}^* -derivation h is called *regular* iff for every subterm $\mathbf{E}h_0$ of h we have $\text{last}(h_0) \in \{\mathbf{E}, \mathbf{R}_C, \text{Ind}_{\mathbf{F}}^{y,t}\}.$ – Obviously each $\psi_n(d)$ is regular.

$C[k] := \begin{cases} A_x(k) & \text{if } C = QxA \text{ with } Q \in \{\forall, \exists\} \\ A_k & \text{if } C = A_0 \circ A_1 \text{ with } \circ \in \{\wedge, \vee\} \text{ and } k \in \{0, 1\} \end{cases}$

Lemma 3

Let h be a closed \mathbf{Z}^* -derivation.

- a) If $\text{tp}(h) = \text{Rep}$ then there are \mathbf{a}, h' such that $h = \mathbf{a}\{h'\}, h[0] = \mathbf{a}\{h'[0]\}$ and either $h' = \mathbf{E}^m \text{Ind}_{\mathbf{F}}^{y,t} h''$ or $h' = \mathbf{E}^{m+1} h''$ & $\text{tp}(h'') = \text{Cut}_B.$
- b) If $\text{tp}(h) = \text{Cut}_B$ then there are \mathbf{b}, C, h_0, h_1 such that $\text{hgt}^*(\mathbf{b}) = 0,$
 $h = \mathbf{b}\{\mathbf{R}_C h_0 h_1\}, h[i] = \mathbf{b}\{(\mathbf{R}_C h_0 h_1)[i]\},$ and either
 - (1) $\text{tp}(h_0) = \wedge_C$ & $\text{tp}(h_1) = \vee_{-C}^k$ & $B = C[k]$ or
 - (2) $\text{tp}(h_0) = \vee_C^k$ & $\text{tp}(h_1) = \wedge_{-C}$ & $B = C[k].$
- c) If h is regular and $\text{tp}(h) = \wedge_C$ or \vee_C^k then there are \mathbf{c}, h_0, h_1 such that $C \notin \text{Cut}(\mathbf{c})$ and
 $[h = \mathbf{c}\{\wedge_C^y h_0\} \& h[i] = \mathbf{c}\{h_0(y/i)\}]$ or $[h = \mathbf{c}\{\wedge_C h_0 h_1\} \& h[i] = \mathbf{c}\{h_i\}]$ or
 $[h = \mathbf{c}\{\vee_C^k h_0\} \& h[0] = \mathbf{c}\{h_0\}].$

Proof:

a) By definition of $\text{tp}(h)$ one of the following cases holds:

1. $h = \mathbf{E}^m \text{Ind}_{\mathbf{F}}^{y,t} \tilde{h}:$ Then $\mathbf{a} := *, h' := h.$
2. $h = \mathbf{E}^n \tilde{h}$ with $\text{last}(\tilde{h}) \neq \mathbf{E}, \text{Ind}:$

2.1. $\text{tp}(\tilde{h}) = \text{Cut}_B$ & $n > 0$: Then $\mathfrak{a} := *$, $h' := h$.

2.2. $\text{tp}(\tilde{h}) = \text{Rep}$: Then $\tilde{h} = \text{R}_C h_0 h_1$ and (w.l.o.g) $\text{tp}(h_0) = \text{Rep}$. By IH $h_0 = \mathfrak{a}_0\{h'\}$ with $h_0[0] = \mathfrak{a}_0\{h'[0]\}$ and $h' = \mathbf{E}^m \text{Ind}_F^{y,t} h''$ or $h' = \mathbf{E}^{m+1} h''$ & $\text{tp}(h'') = \text{Cut}_B$. Now for $\mathfrak{a} := \mathbf{E}^n \text{R}_C \mathfrak{a}_0 h_1$ we have $h = \mathfrak{a}\{h'\}$ and $h[0] = \mathbf{E}^n \text{R}_C h_0[0] h_1 = \mathbf{E}^n \text{R}_C \mathfrak{a}_0\{h'[0]\} h_1 = \mathfrak{a}\{h'[0]\}$.

b) Assume that $\text{tp}(h) = \text{Cut}_B$. Then one of the following cases holds:

1. $h = \text{R}_C h_0 h_1$ and $[(\text{tp}(h_0) = \wedge_C \ \& \ \text{tp}(h_1) = \bigvee_{-C}^k \ \& \ B = C[k]) \ \text{or} \ (\text{tp}(h_0) = \bigvee_C^k \ \& \ \text{tp}(h_1) = \wedge_{-C} \ \& \ B = C[k])]$: The claim holds for $\mathfrak{b} := *$.

2. $h = \text{R}_D h'_0 h'_1$ and (w.l.o.g.) $\text{tp}(h'_0) = \text{tp}(h)$ & $h[i] = \text{R}_D h'_0[i] h'_1$:

By IH there are $\mathfrak{b}_0, C, h_0, h_1$ such that $\text{hgt}^*(\mathfrak{b}_0) = 0$, $h'_0 = \mathfrak{b}_0\{\text{R}_C h_0 h_1\}$, $h'_0[i] = \mathfrak{b}_0\{(\text{R}_C h_0 h_1)[i]\}$ and one of the subcases (1),(2) holds. Let $\mathfrak{b} := \text{R}_D \mathfrak{b}_0 h'_1$. Then $h = \mathfrak{b}\{\text{R}_C h_0 h_1\}$, $h[i] = \text{R}_D h'_0[i] h'_1 = \text{R}_D \mathfrak{b}_0\{(\text{R}_C h_0 h_1)[i]\} h'_1 = \mathfrak{b}\{(\text{R}_C h_0 h_1)[i]\}$, and $\text{hgt}^*(\mathfrak{b}) = \text{hgt}^*(\mathfrak{b}_0) = 0$.

c) Assume that h is regular, and $\text{tp}(h) = \wedge_C$ with $C = \forall xA$.

Then one of the following cases holds:

1. $h = \bigwedge_{\forall xA}^y h_0$: Then the claim holds for $\mathfrak{c} := *$.

2. $h = \mathbf{E}^m \text{R}_D h'_0 h'_1$ with (w.l.o.g.) $\text{tp}(h) = \text{tp}(h'_0)$ and $D \neq C$: By IH $h'_0 = \mathfrak{c}_0\{\bigwedge_C^y h_0\}$ and $h'_0[i] = \mathfrak{c}_0\{h_0(y/i)\}$ with $C \notin \text{Cut}(\mathfrak{c}_0)$. Let $\mathfrak{c} := \mathbf{E}^m \text{R}_D \mathfrak{c}_0 h'_1$. Then $h = \mathfrak{c}\{\bigwedge_{\forall xA}^y h_0\}$, $h[i] = \mathbf{E}^m \text{R}_D h'_0[i] h'_1 = \mathbf{E}^m \text{R}_D \mathfrak{c}_0\{h_0(y/i)\} h'_1 = \mathfrak{c}\{h_0(y/i)\}$ and $C \notin \{D\} \cup \text{Cut}(\mathfrak{c}_0) = \text{Cut}(\mathfrak{c})$.

Theorem 5

Assume that $\Gamma(d) = \emptyset$ and let $h := \psi_0(d)$.

Then $\text{tp}(h) = \text{Rep}$ and one of the following two cases holds:

(I) $h = \mathfrak{a}\{\mathbf{E}^m \text{Ind}_F^{y,t} h_0\}$, $h[0] = \mathfrak{a}\{\mathbf{E}^m (\text{Ind}_F^{y,t} h_0)[0]\}$,

(II) $h = \mathfrak{a}\{\mathbf{E}^{m+1} \mathfrak{b}\{\text{R}_C h_0 h_1\}\}$, $h[0] = \mathfrak{a}\{\mathbf{E}^m \text{R}_{C[k]} \mathbf{E} \mathfrak{b}\{\text{R}_C h_0^- h_1\} \mathbf{E} \mathfrak{b}\{\text{R}_C h_0 h_1^-\}\}$

and either

(1) $\text{tp}(h_0) = \wedge_C \ \& \ \text{tp}(h_1) = \bigvee_{-C}^k \ \& \ h_0^- = h_0[k] \ \& \ h_1^- = h_1[0]$ or

(2) $\text{tp}(h_0) = \bigvee_C^k \ \& \ \text{tp}(h_1) = \wedge_{-C} \ \& \ h_0^- = h_0[0] \ \& \ h_1^- = h_1[k]$.

Moreover $\text{hgt}^*(\mathfrak{b}) = 0$ and $\text{hgt}(\mathfrak{a}) + m + 1 = \text{rk}(\tilde{C}) = \max\{\text{hgt}(\mathfrak{b}), \text{rk}(C)\}$

with $\tilde{C} := \begin{cases} C & \text{if } \mathfrak{b} = * \\ D & \text{if } \text{last}(\mathfrak{b}) = \text{R}_D \end{cases}$.

Proof:

We have $\Gamma(h) = \emptyset$ & $\text{deg}(h) = 0$ and therefore (by Theorem 3) $\text{tp}(h) = \text{Rep}$. Further h is regular. Now let us assume that (I) does not hold.

Then according to L.3a) $h = \mathfrak{a}\{\mathbf{E}^{m+1} h''\}$ with $\text{tp}(h'') = \text{Cut}_B$ and

$h[0] = \mathfrak{a}\{(\mathbf{E}^{m+1} h'')[0]\} = \mathfrak{a}\{\mathbf{E}^m (\mathbf{E} h'')[0]\} = \mathfrak{a}\{\mathbf{E}^m \text{R}_B \mathbf{E} h''[0] \mathbf{E} h''[1]\}$.

By L.3b) we get $h'' = \mathfrak{b}\{\text{R}_C h_0 h_1\}$, $h''[i] = \mathfrak{b}\{(\text{R}_C h_0 h_1)[i]\}$ with $\text{hgt}^*(\mathfrak{b}) = 0$, and

— in subcase (1) — $\text{tp}(h_0) = \wedge_C \ \& \ \text{tp}(h_1) = \bigvee_{-C}^k \ \& \ B = C[k]$.

Putting things together yields

Now the last part of Theorem 4, i.e. the relation $O(\text{red}(d), \langle \rangle) < O(d, \langle \rangle)$, immediately follows from [Ge38]. But we think it may be useful to include an independent proof here.

Lemma 4 $n \leq k \Rightarrow o(\psi_n(d)) \leq \omega_{k-n} o(\psi_k(d))$.

Proof:

Abbreviation: $o_n(d) := o(\psi_n(d))$.

1. $d = R_C d_0 d_1$ and $l := \max\{n, \text{rk}(C)\}$:

1.1. $l \leq k$: $o_n(d) = \omega_{l-n}(o_l(d_0) \# o_l(d_1)) \stackrel{\text{IH}}{\leq} \omega_{l-n}(\omega_{k-l} o_k(d_0) \# \omega_{k-l} o_k(d_1)) \leq \omega_{l-n}(\omega_{k-l} o_k(d_0) \# o_k(d_1)) = \omega_{k-n} o_k(d)$.

1.2. $n \leq k < l$:

$o_n(d) = \omega_{l-n}(o_l(d_0) \# o_l(d_1)) = \omega_{k-n} \omega_{l-k}(o_l(d_0) \# o_l(d_1)) = \omega_{k-n} o_k(d)$.

2. $d = \text{Ind}_F^{y,t}$: analogous to 1.

3. $d = \mathcal{I}d_0 \dots d_{m-1}$ otherwise: $o_n(d) = (\sup_{i < m} o_n(d_i)) + 1 \stackrel{\text{IH}}{\leq} (\sup_{i < m} \omega_{k-n} o_k(d_i)) + 1 \leq \omega_{k-n} ((\sup_{i < m} o_k(d_i)) + 1) = \omega_{k-n} o_k(d)$.

Lemma 5

$\text{deg}(h) \leq n \Rightarrow o(\psi_n \phi(h)) \leq o(h)$.

Proof:

1. $h = \mathbf{E}h_0$ with $\text{deg}(h_0) \leq n+1$: $o(\psi_n \phi(h)) = o(\psi_n \phi(h_0)) \stackrel{\text{L.4}}{\leq}$

$\omega_1 o(\psi_{n+1} \phi(h_0)) \stackrel{\text{IH}}{\leq} \omega_1 o(h_0) = o(h)$.

2. $h = R_C h_0 h_1$ with $\max\{\text{rk}(C), \text{deg}(h_0), \text{deg}(h_1)\} \leq n$:

$o(\psi_n \phi(h)) = o(\psi_n R_C \phi(h_0) \phi(h_1)) \stackrel{\text{rk}(C) \leq n}{\leq} o(R_C \psi_n \phi(h_0) \psi_n \phi(h_1)) =$

$o(\psi_n \phi(h_0) \# o(\psi_n \phi(h_1))) \stackrel{\text{IH}}{\leq} o(h_0) \# o(h_1) = o(h)$.

3. $h = \text{Ind}_F^{y,t} h_0$: analogous to 2.

4. $h = \mathcal{I}h_0 \dots h_{m-1}$ otherwise: immediately by IH.

Proof of $O(\text{red}(d), \langle \rangle) < O(d, \langle \rangle)$: Let $h := \psi_0(d)[0]$.

From $\text{deg}(\psi_0(d)) = 0$ it follows by Theorem 3 that $\text{deg}(h) = 0$. Hence

$O(\text{red}(d), \langle \rangle) \stackrel{\text{L.1}}{=} o(\psi_0 \text{red}(d)) = o(\psi_0 \phi(h)) \stackrel{\text{L.5}}{\leq} o(h) \stackrel{\text{Th.3}}{<} o(\psi_0(d)) \stackrel{\text{L.1}}{=} O(d, \langle \rangle)$.

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